

Generative Surrogate Models for Differentiable Optimization of a Parallel-Plate Avalanche Counter with Optical Readout

María Pereira Martínez, Pietro Vischia, Xabier Cid Vidal

XVII CPAN Days, Valencia

November 20th 2025



I. Introduction

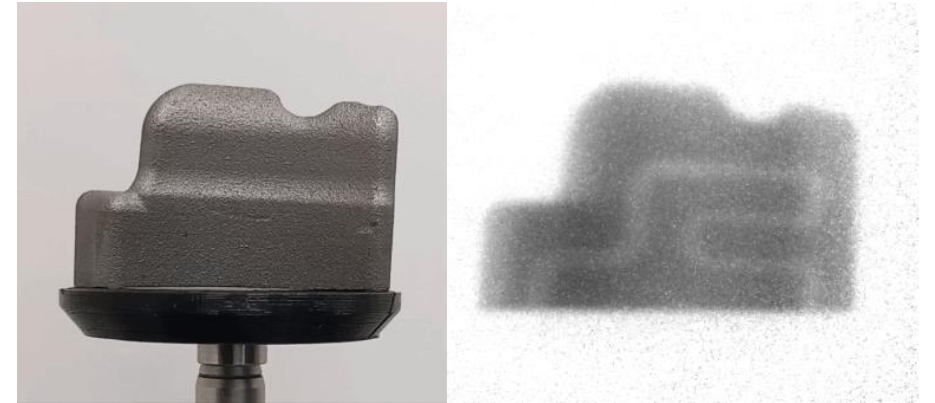
Neutron tomography



Tomography by **emission and detection of neutrons**
for non-destructive tests.

High penetration, effective for dense materials like metals and alloys.

Metal industry, additive manufacturing,
border security...



Frances Yassid
Ayyad Limonge



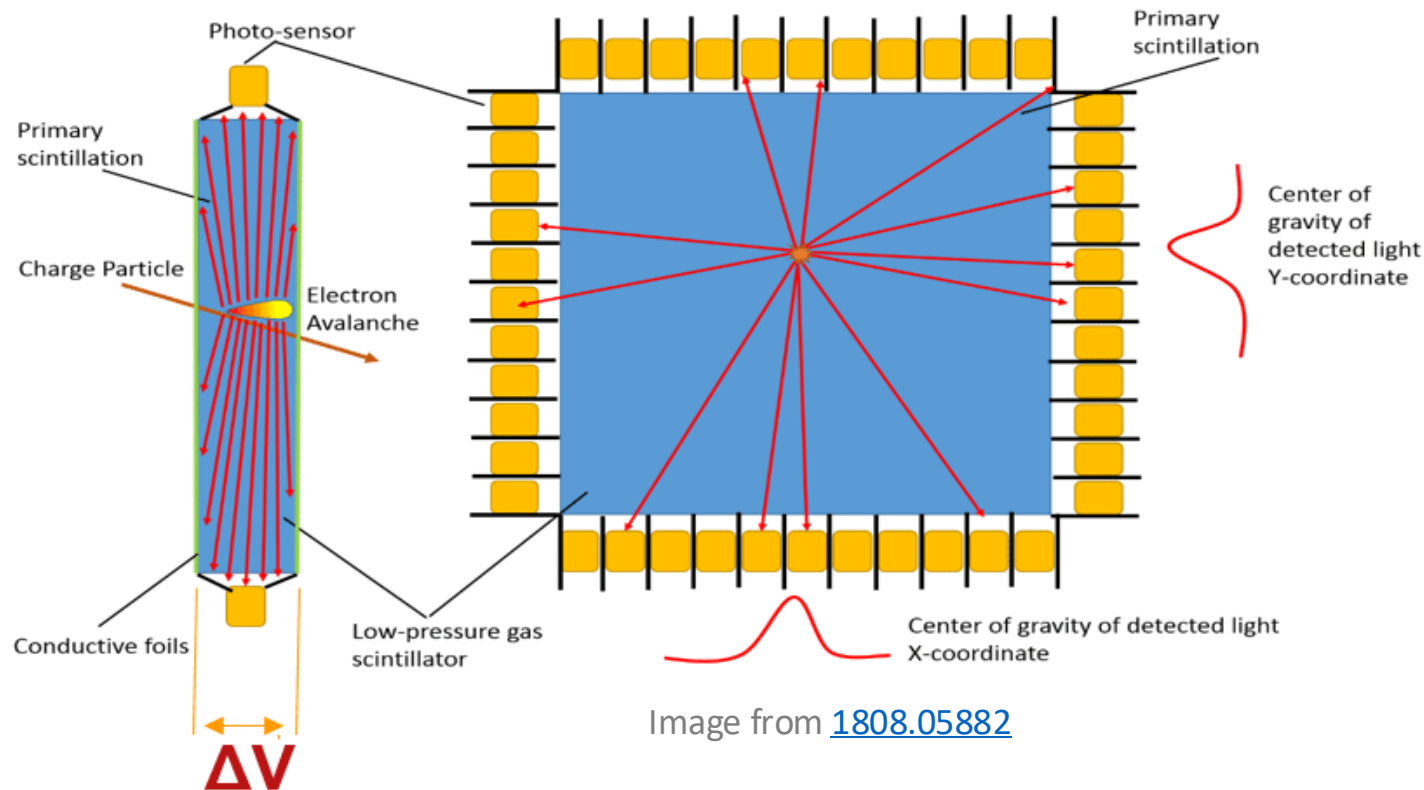
Pablo Cabanelas
Eiras

Images from [Neutron Insights](https://neutroninsights.com) website

What do we want to do?

Optimize the neutron tomography system but... **where do we start?**

Optical Parallel-Plate Avalanche Counter

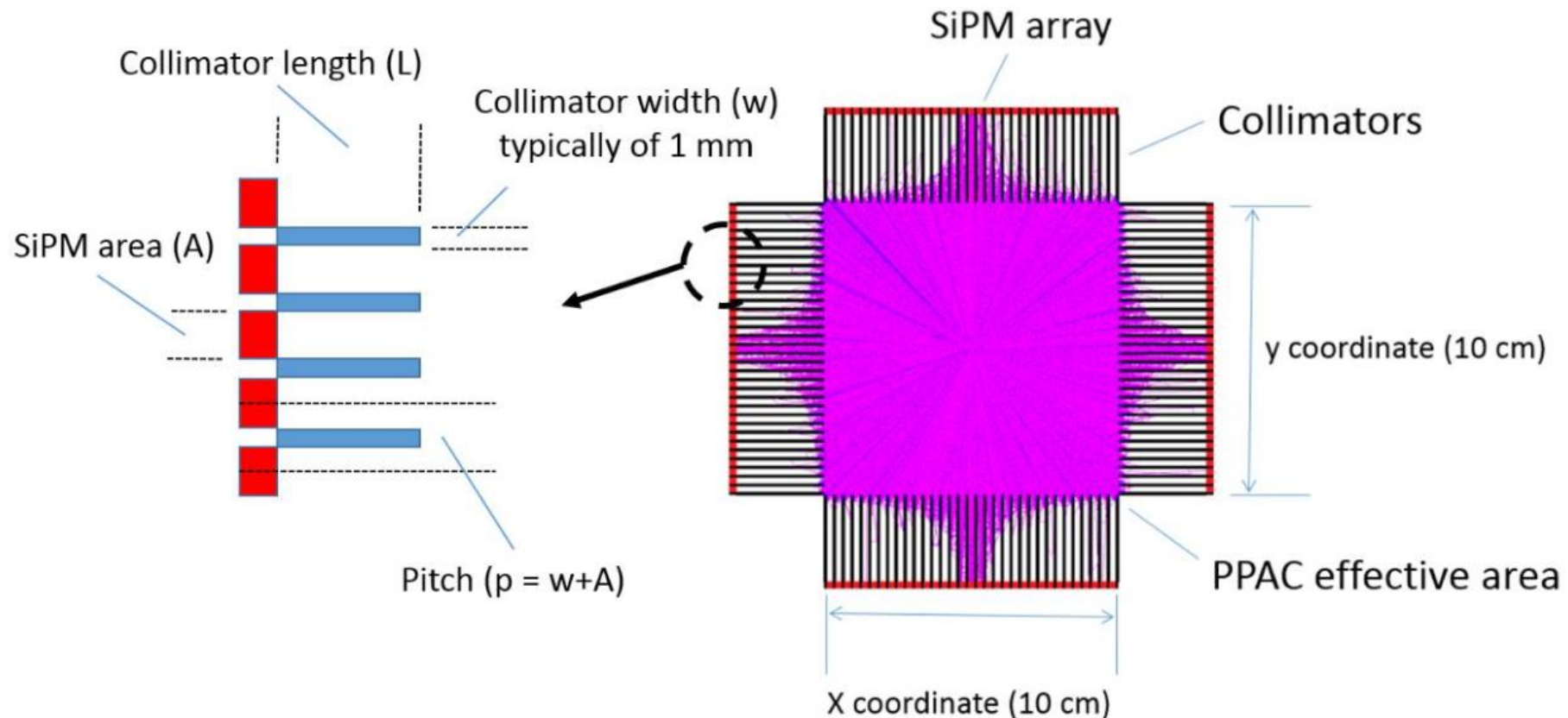


- Parallel-plates filled with a **high electroluminescence yield gas (CF₄)**.
- Charged particles crossing active volume ionize medium and produce an avalanche.
- Electroluminescence light detected by 4 arrays of small, **collimated silicon photomultipliers (SiPMs)**.

Optical Parallel Plate Avalanche Counter

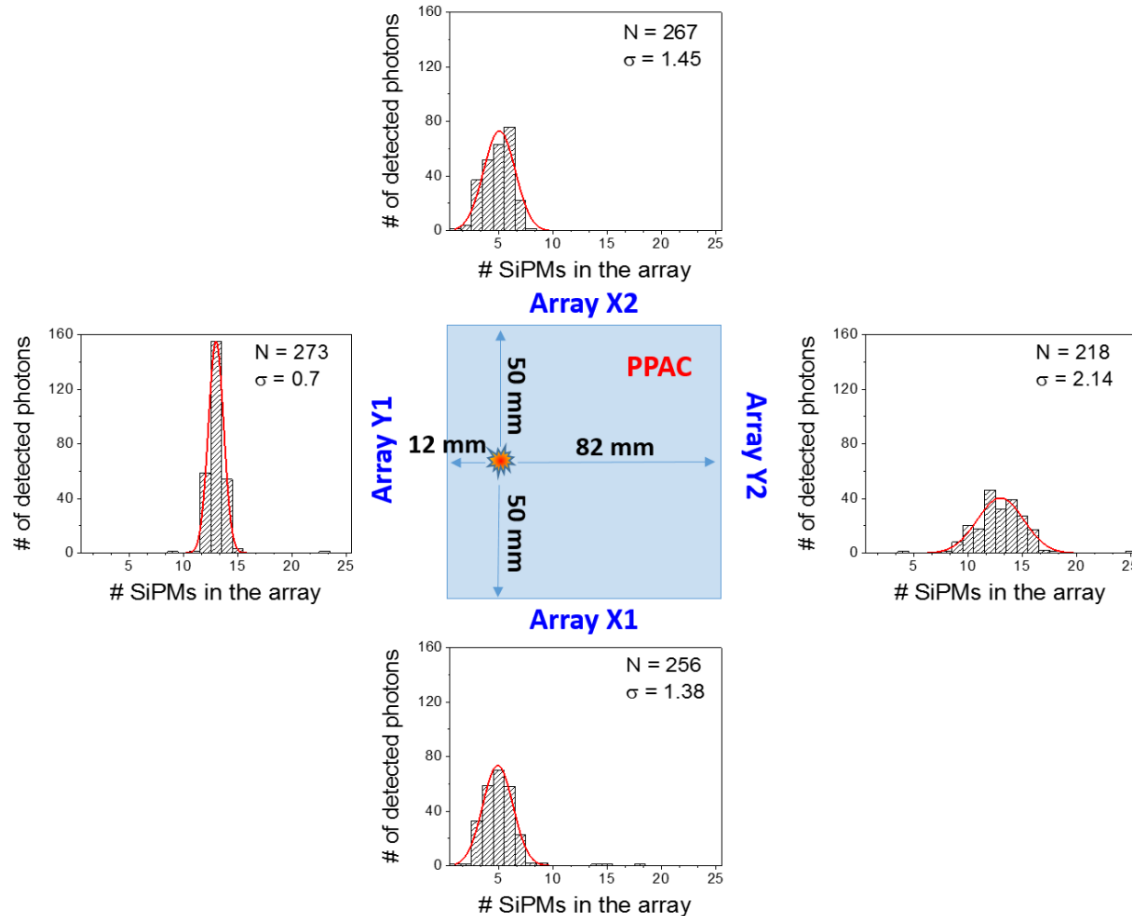
Geant4 model of a $10 \times 10 \text{ cm}^2$ O-PPAC, 33 SiPMs per array

Example of an event triggered by an impinging alpha particle:



Reconstruction of the position

Reconstructed position (\hat{x} , \hat{y}) obtained from the **number of photons detected in each SiPM**



Weighted average

$$\hat{x} = \frac{\left(\frac{P_{x1} \cdot N_{x1}}{\sigma_{x1}} + \frac{P_{x2} \cdot N_{x2}}{\sigma_{x2}} \right)}{\left(\frac{N_{x1}}{\sigma_{x1}} + \frac{N_{x2}}{\sigma_{x2}} \right)}$$

$$\hat{y} = \frac{\left(\frac{P_{y1} \cdot N_{y1}}{\sigma_{y1}} + \frac{P_{y2} \cdot N_{y2}}{\sigma_{y2}} \right)}{\left(\frac{N_{y1}}{\sigma_{y1}} + \frac{N_{y2}}{\sigma_{y2}} \right)}$$

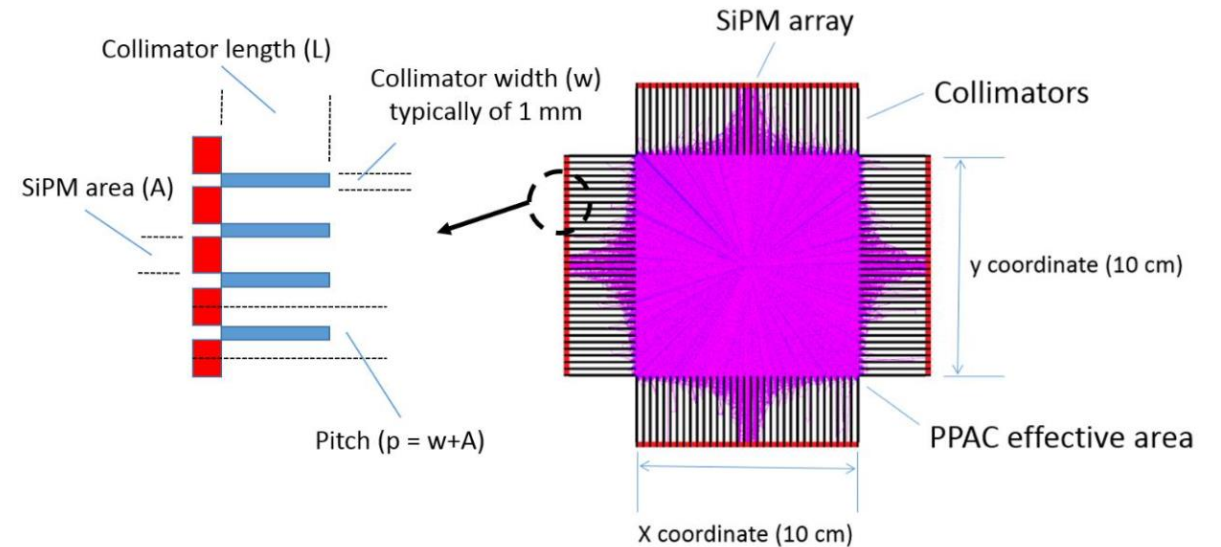
Parameters of interest

- **Collimator Length (L):**

- Large $L \rightarrow$ better resolution, poor statistics
- Small $L \rightarrow$ worse resolution, better statistics

- **Pressure (p):**

- High pressure \rightarrow higher photon statistics



What is the optimal combination of these parameters?

The background is a solid dark blue color. It is decorated with a complex network of thin, light blue lines that connect various points. Some of these points are highlighted as small, bright blue dots. The lines and dots are scattered across the frame, with a higher concentration in the upper-left and lower-right corners, creating a sense of depth and connectivity.

2. Differentiable programming for experiment design

Differentiable programming for experiment design

Designing experiments is a **challenging task**.

- Number of parameters can be **too high**.
- Correlations between parameters can be **non-trivial**.
- Traditional approaches are **computationally costly**.

**Development of deep learning techniques
allows us to explore new approaches**



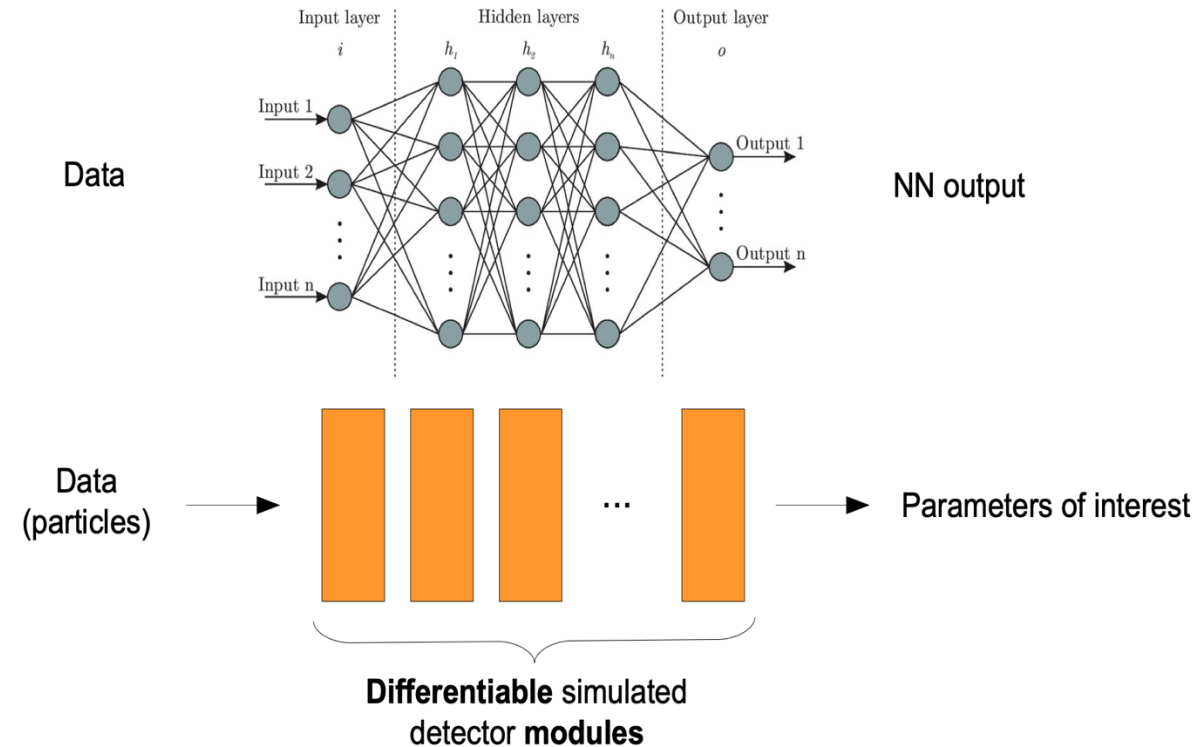
Differentiable programming for experiment design

1. Model detector modules as differentiable functions of n parameters ϕ_n .

2. Set loss function:

$$\mathcal{L} = \mathcal{L}(\phi_1, \phi_2, \dots, \phi_n)$$

3. Minimise \mathcal{L} w.r.t. ϕ_n with automatic differentiation.



Minimization of objective function through automatic differentiation

Image from [Julien Donini - Seminaire LPNHE - 14/02/2022](#)

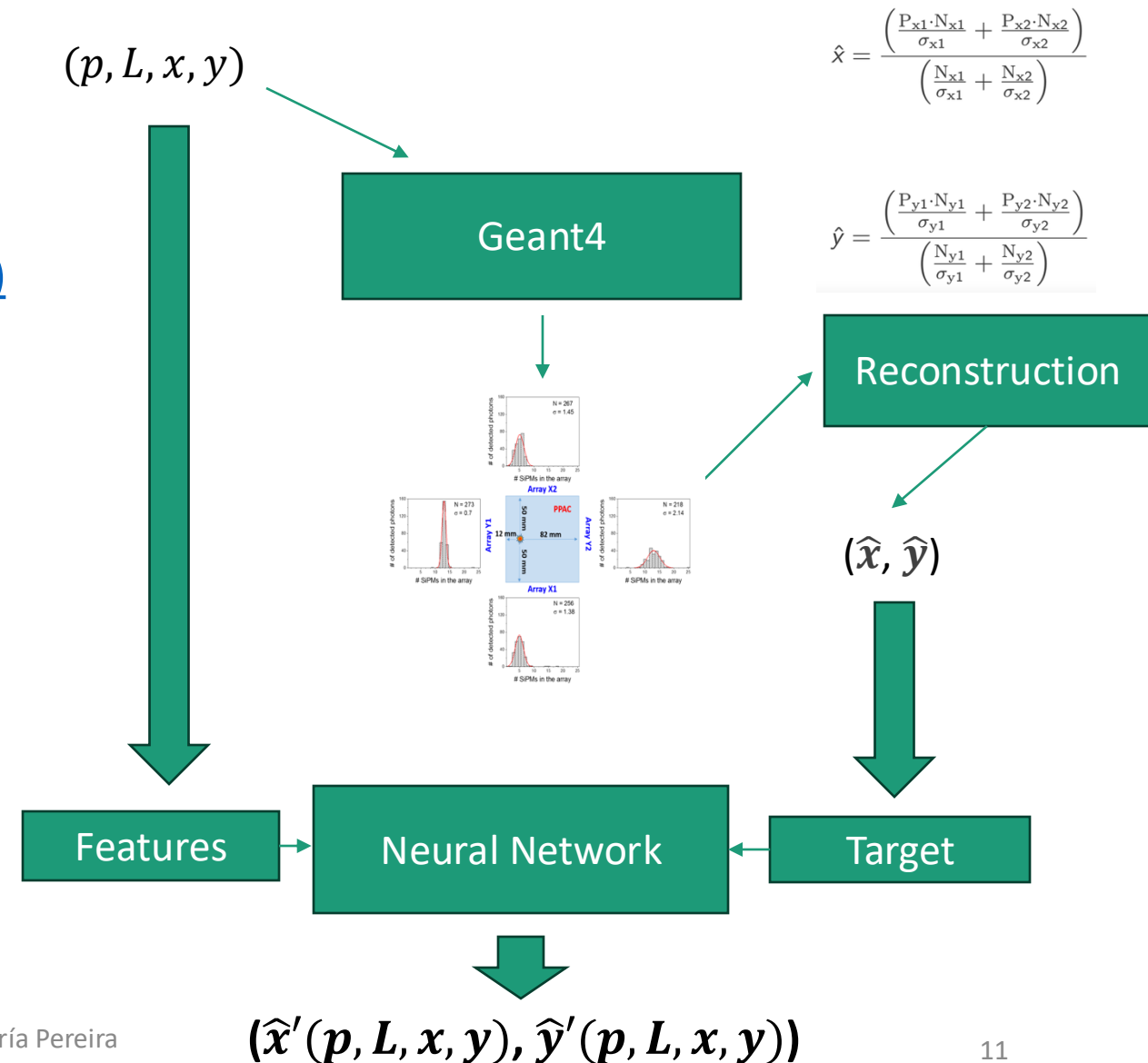


3. Automatic optimization of the O-PPAC detector

Automatic optimization of O-PPAC

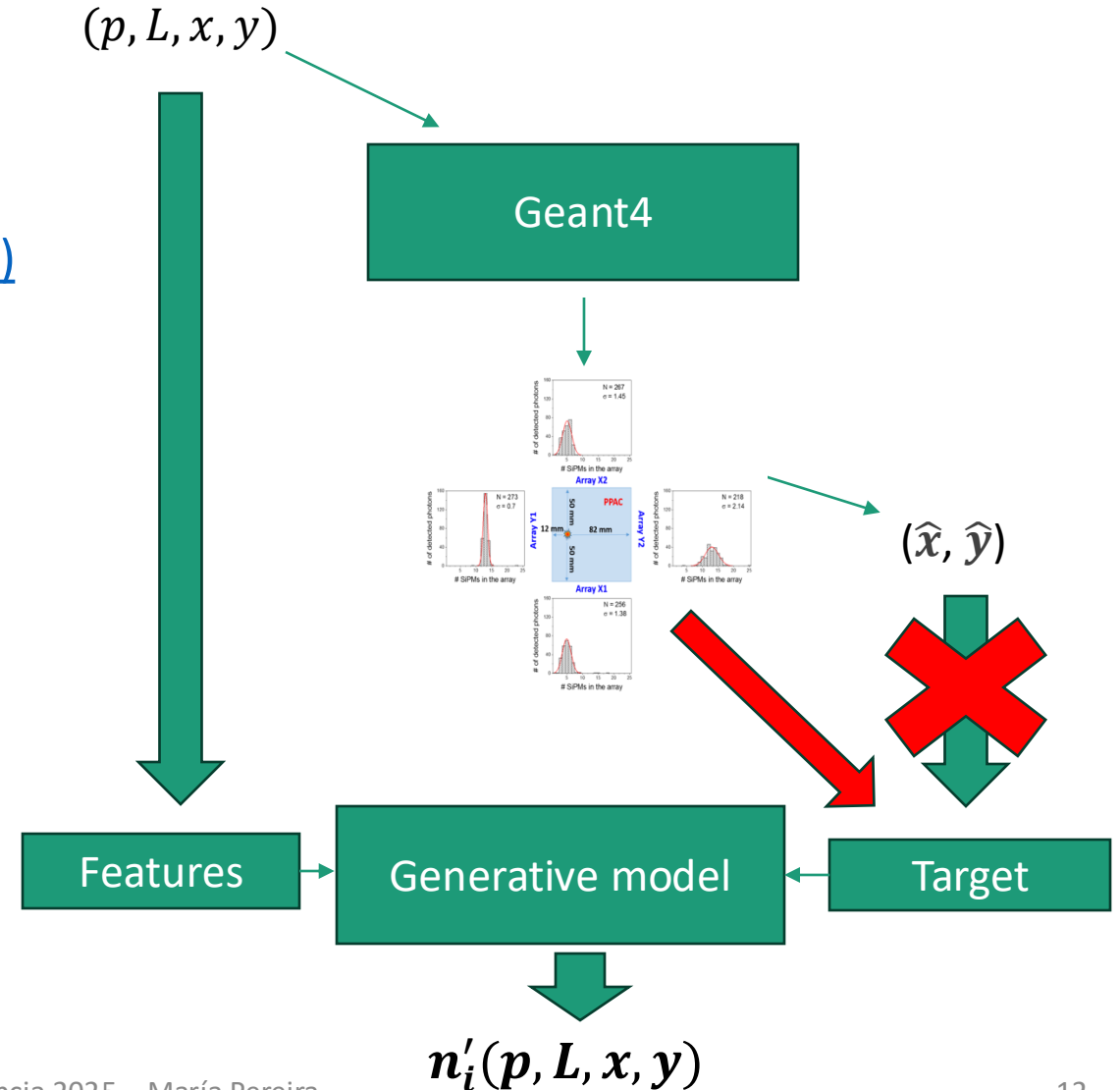
- **Geant4 is not differentiable.**
- Ongoing efforts on making it differentiable
([Differentiable EM showers in Geant4 - 2405.07944](#))
- **Surrogate modelling** is a practical workaround.
- **Approaches:**

1. Train a NN to **predict the reconstructed position as a function of (p, L, x, y) .**



Automatic optimization of O-PPAC

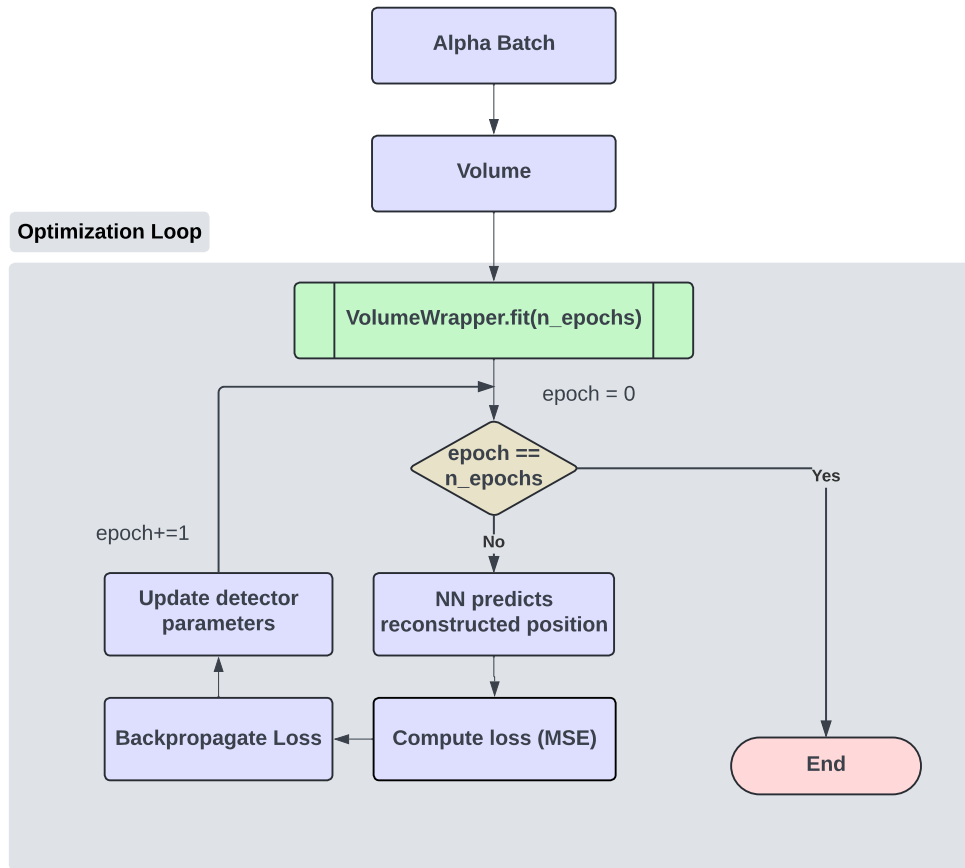
- **Geant4 is not differentiable.**
- Ongoing efforts on making it differentiable
([Differentiable EM showers in Geant4 - 2405.07944](#))
- Surrogate modelling is a practical workaround.
- **Approaches:**
 1. Train a NN to **predict the reconstructed position** as a function of (p, L, x, y) .
 2. Train a **generative model** to predict photon distributions from (p, L, x, y) .





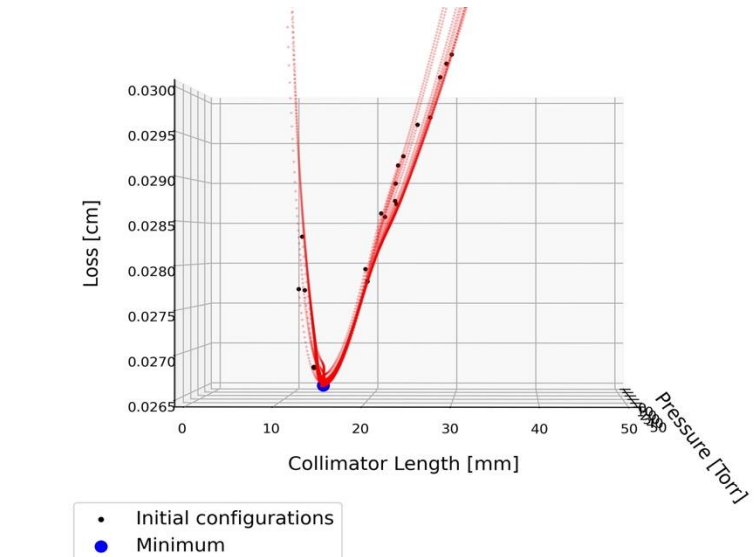
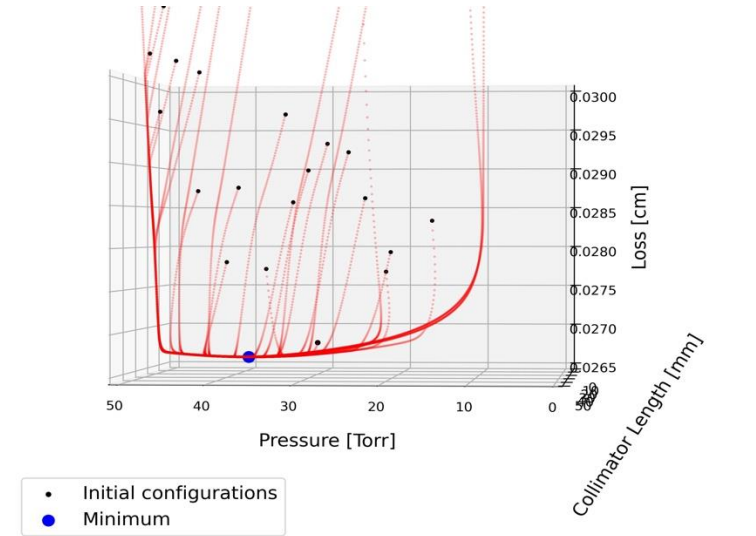
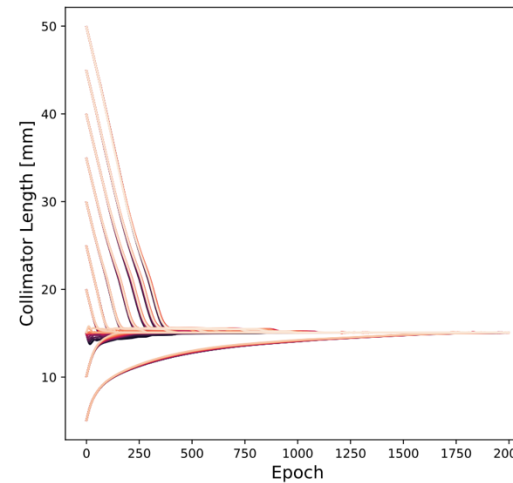
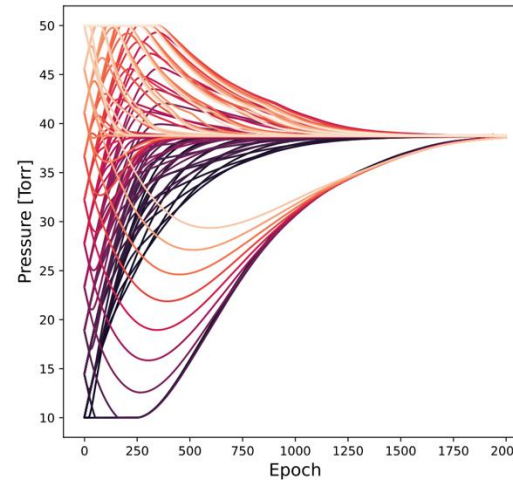
3.1. Neural Network Surrogate

1. NN surrogate



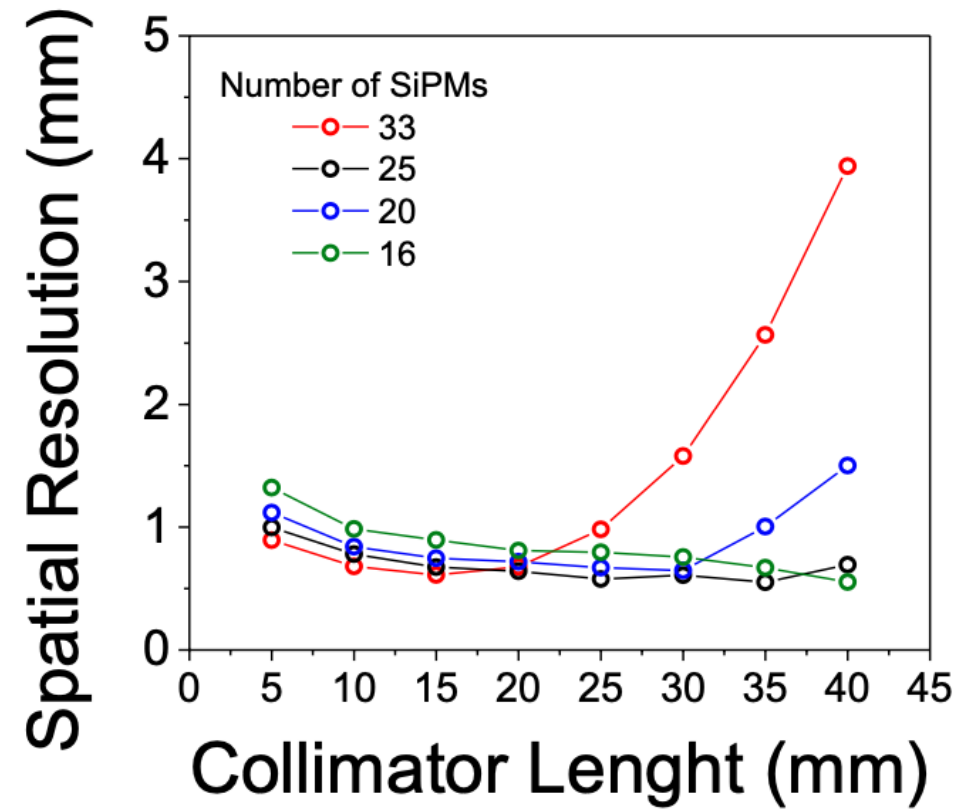
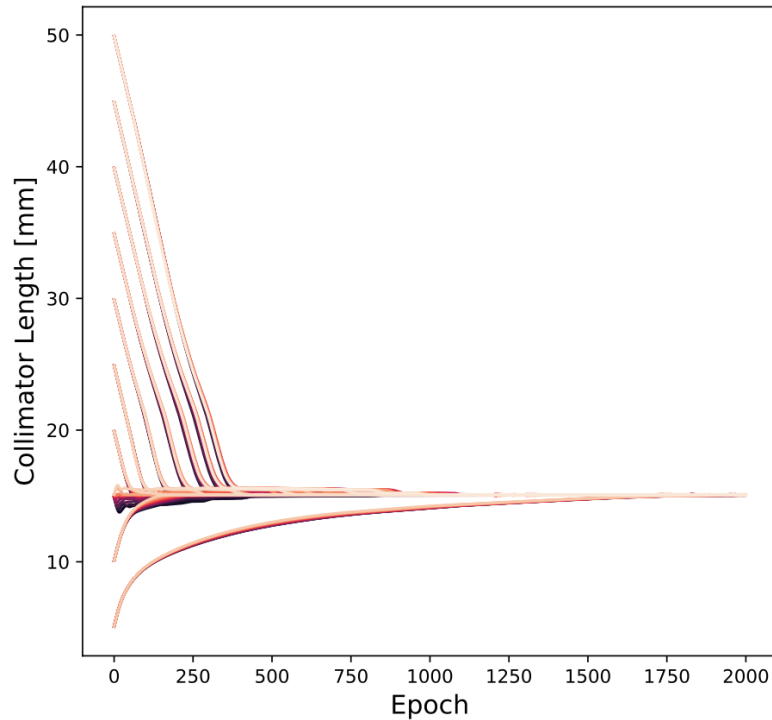
Results published in *Particles* **2025**, 8(1), 26; <https://doi.org/10.3390/particles8010026>

Solution remarkably stable **regardless of initial configuration**



1. NN surrogate

Collimator length result matches the traditional approach: [10.1088/1748-0221/13/10/P10006](https://doi.org/10.1088/1748-0221/13/10/P10006)



Results published in *Particles* **2025**, 8(1), 26; <https://doi.org/10.3390/particles8010026>

The background is a solid dark blue. Overlaid on this are several abstract, glowing blue network structures. These structures consist of numerous small, bright blue circular nodes connected by thin, light blue lines. The nodes and lines are arranged in a way that suggests a complex, interconnected system, possibly representing a neural network or a data flow. The structures are primarily located in the upper left and lower right corners, with some lines extending towards the center.

3.2. Generative surrogate

2. Generative Surrogate

- **Why generative surrogates?**

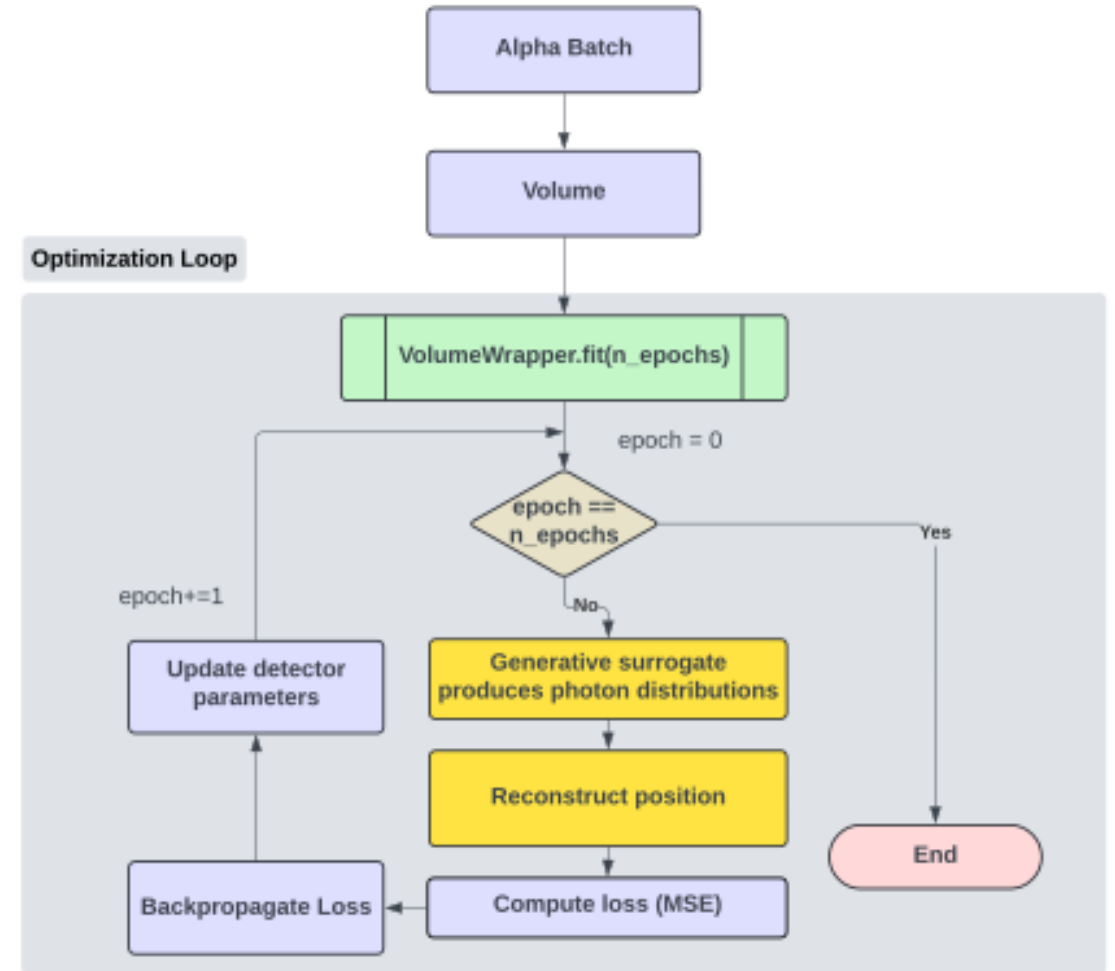
- Can give a more detailed description of detector behaviour.
- Allow us to **skip 'manual' reconstruction step**.
- Freedom to change reconstruction step in the future.
- Trained model will be **used later in a bigger pipeline**.

- **Models we are testing:**

- GP-WGAN
- β -VAE

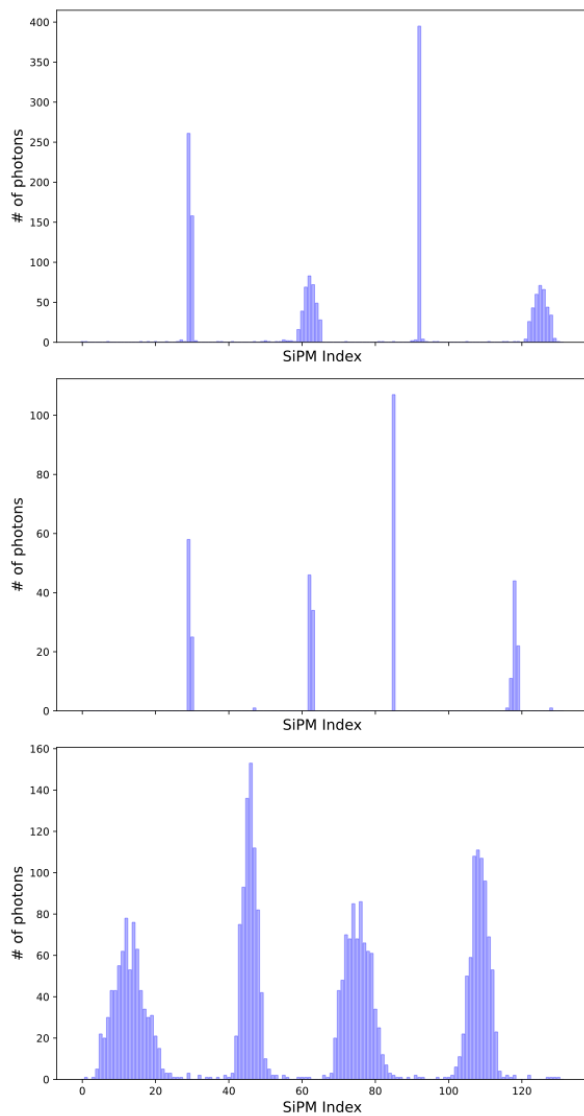
- **Hyperparameter tuning:**

- TPE algorithm parallelised in gpus.

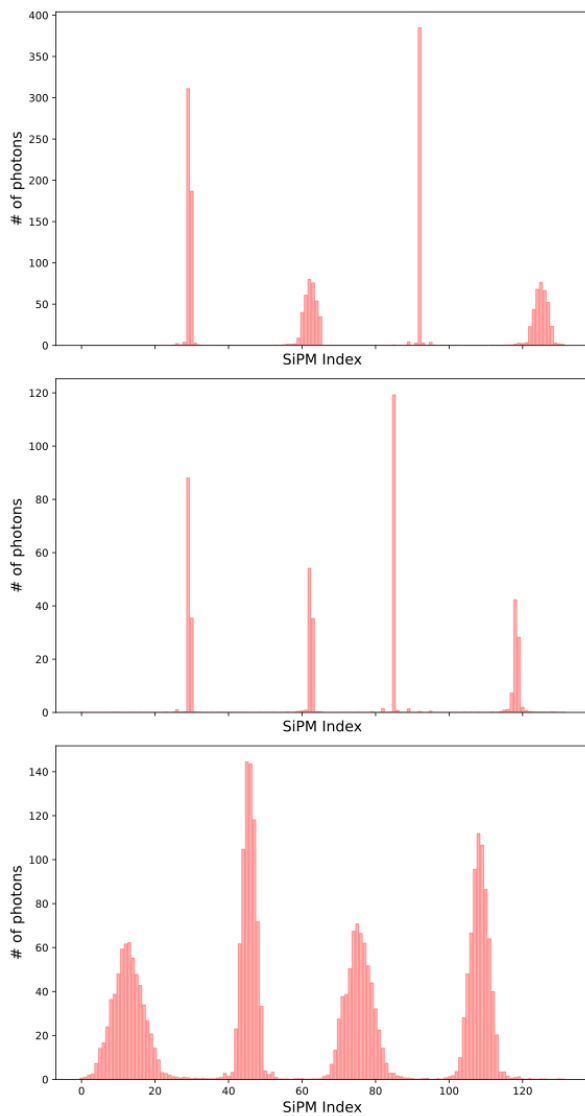


2. Generative Surrogate: Current status and challenges

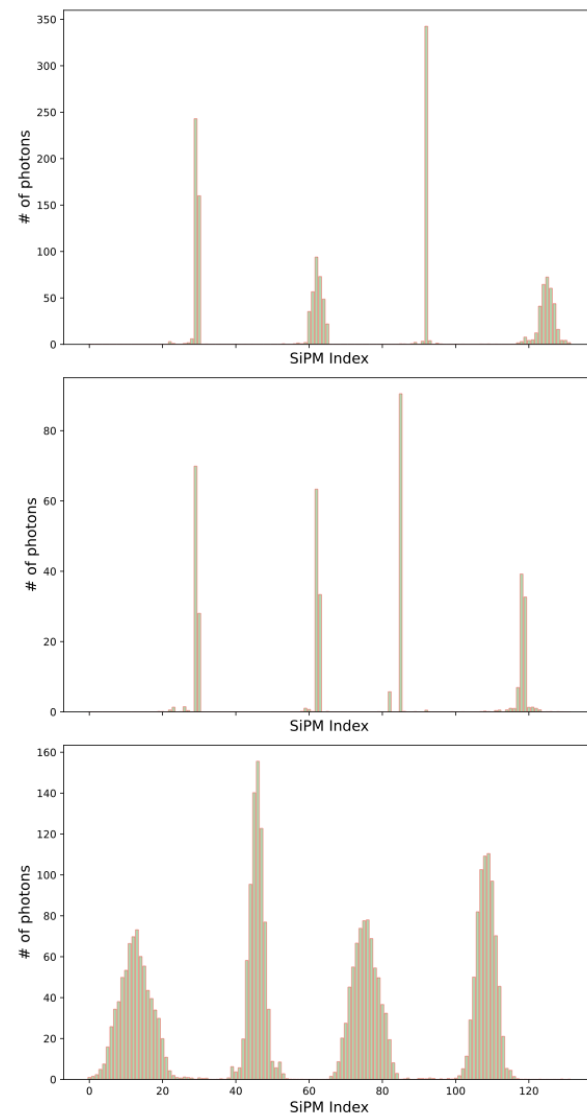
Real events



GP-WGAN (RMSE = 5.2829)

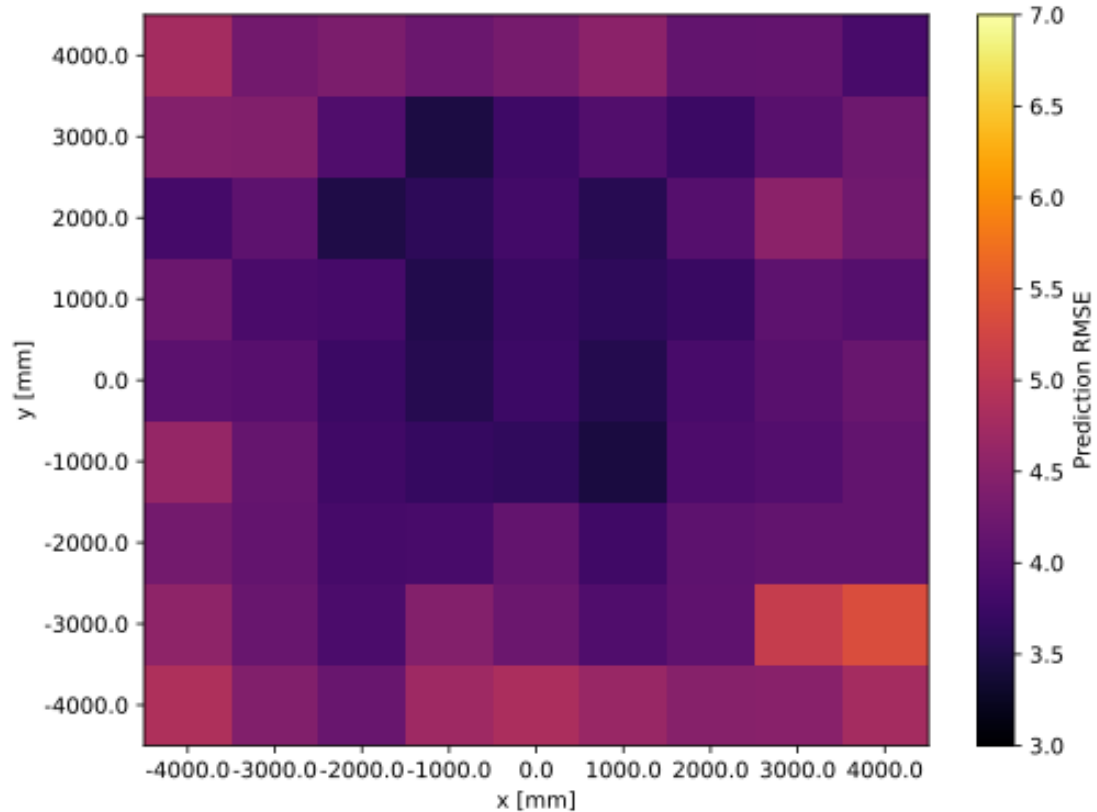


β -VAE (RMSE = 5.2356)

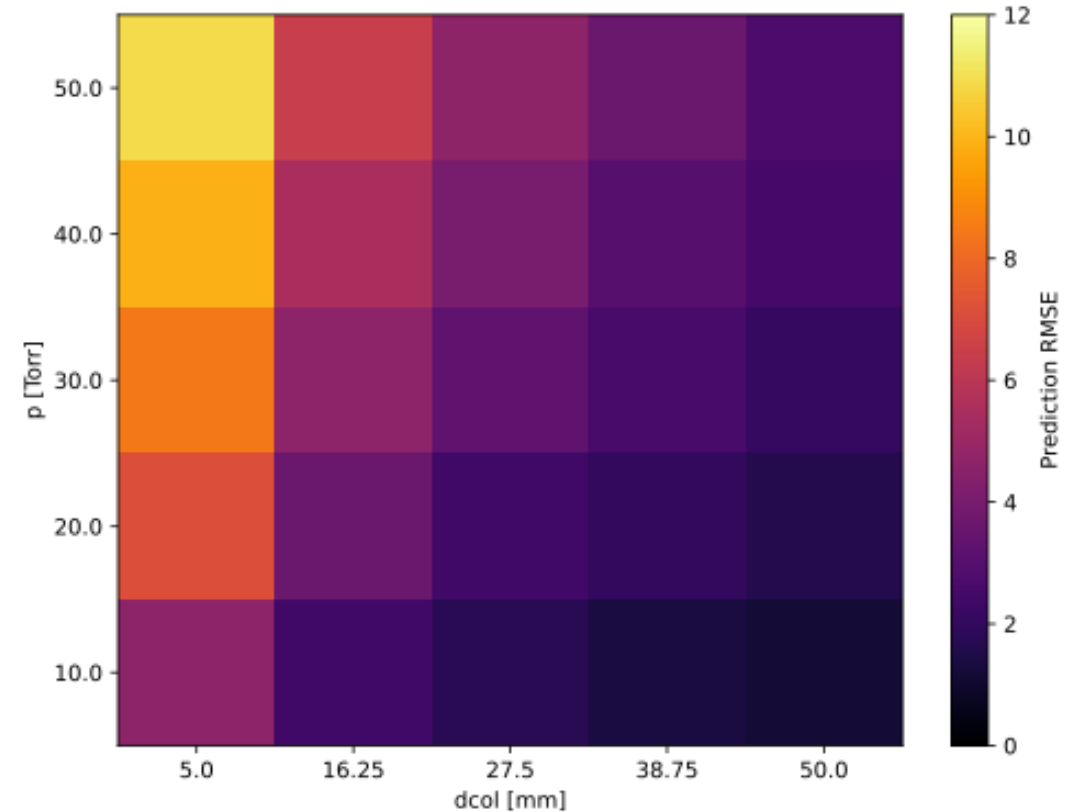


2. Generative Surrogate: Current status and challenges

Behaviour is pretty uniform in x, y



but not so uniform in p, L

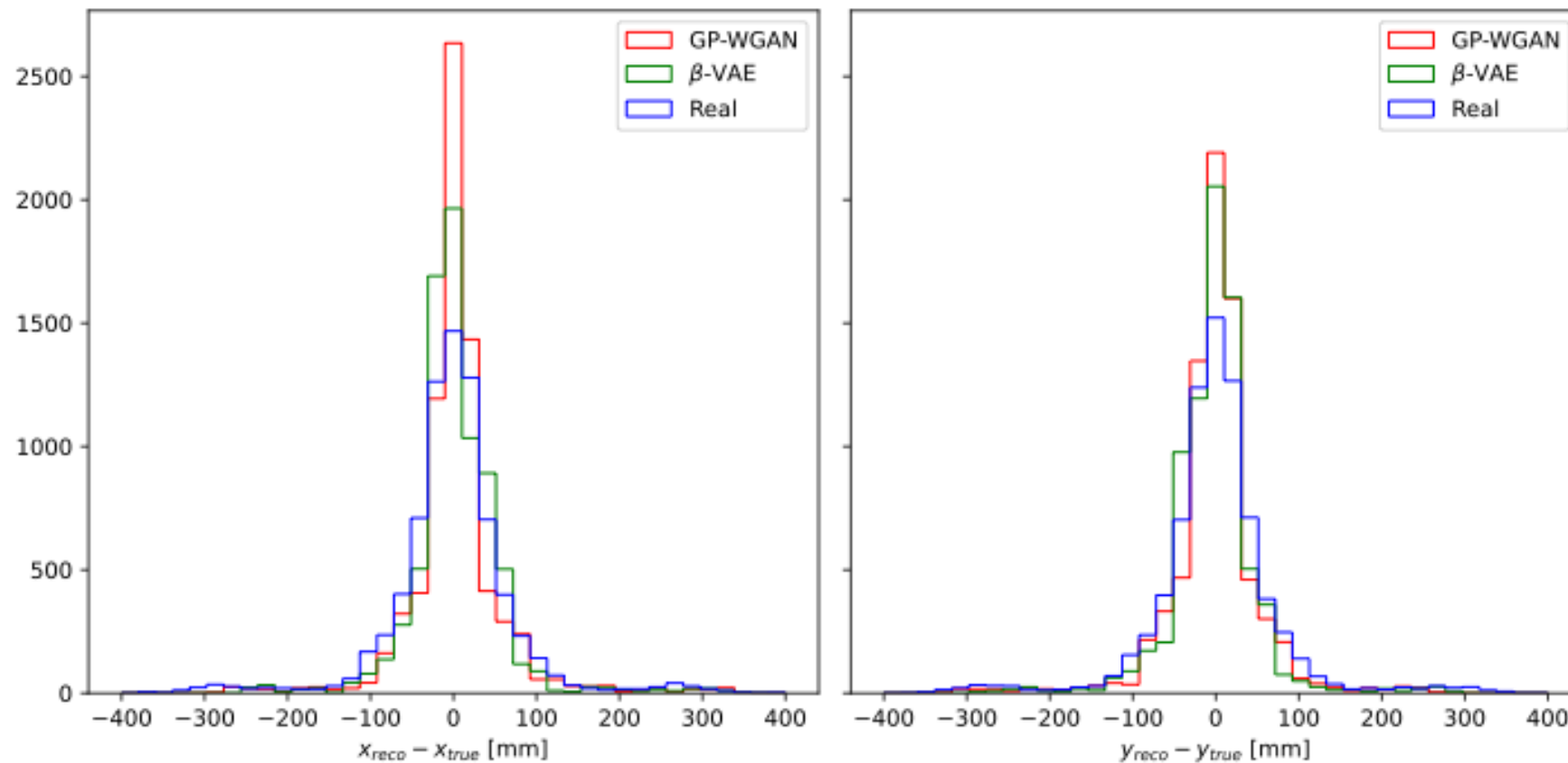


Proposed solutions:

- Train separate models for different regions.
- Penalize bad behaviour in this region through weights in loss function

2. Generative Surrogate: Current status and challenges

- **Interesting parameter:** error in reconstructed position
- β -VAE is better than GP-WGAN but there's room for improvement.



The background is a solid dark blue. It features an abstract network of thin, light blue lines connecting various points. Some of these points are highlighted as glowing, bright blue nodes. The network is more dense in the top-left and bottom-right corners, with lines radiating outwards from the central area where the text is located.

Conclusions

Conclusions



- We are applying **differentiable programming** for the optimization of the O-PPAC detector.
- **With NN surrogate approach:**
 - Solution independent **of the initial configuration**.
 - Collimator length result **aligns with traditional methods**.
- **With generative surrogate approach:**
 - GP-WGANs and β -VAEs show comparable performance.
 - Behaviour is dependent on parameter region.

Next steps



- Improve generative surrogate response throughout the parameter space.
- Try state-of-the-art models:
 - Diffusion models
 - Normalizing flows
- Build pipeline for the full tomography system.

Thank you for your attention!
Questions?

The background is a solid dark blue. It features an abstract network of thin, light blue lines connecting various glowing blue nodes. These nodes are concentrated in the top-left and bottom-right corners, with some lines extending towards the center. The overall effect is a sense of digital connectivity or a complex data structure.

Backup slides

Vanilla GANs (2014) (<https://arxiv.org/abs/1406.2661>)

$$\min_G \max_D V(D, G) = \mathbb{E}_{\mathbf{x} \sim p_{\text{data}}(\mathbf{x})} [\log D(\mathbf{x})] + \mathbb{E}_{\mathbf{z} \sim p_z(\mathbf{z})} [\log (1 - D(G(\mathbf{z})))]$$

- Discriminator tries to classify events as real or fake
- Generator tries to fool the discriminator into thinking that generated events are real

Known problems:

- Training can converge without good results. Loss doesn't give us information of the quality of the samples
- Instability: D and G have to be very coordinated through architecture and learning rate. If not, convergence is not guaranteed.
- **Mode Collapse:** G learns to fool D producing the same event or very few events.
- **Overtrained discriminator:** if D is very good at classifying events, G cannot learn

Wasserstein GANs (2017) (<https://arxiv.org/pdf/1701.07875>)

The *Earth-Mover* (EM) distance or Wasserstein-1

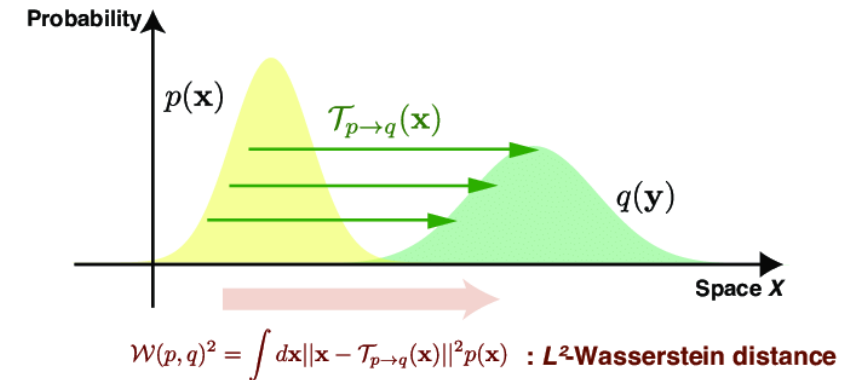
$$W(\mathbb{P}_r, \mathbb{P}_g) = \inf_{\gamma \in \Pi(\mathbb{P}_r, \mathbb{P}_g)} \mathbb{E}_{(x,y) \sim \gamma} [\|x - y\|] ,$$

On the other hand, the Kantorovich-Rubinstein duality [22] tells us that

$$W(\mathbb{P}_r, \mathbb{P}_\theta) = \sup_{\|f\|_L \leq 1} \mathbb{E}_{x \sim \mathbb{P}_r} [f(x)] - \mathbb{E}_{x \sim \mathbb{P}_\theta} [f(x)]$$

We can use the critic (old discriminator) function as an estimator of the W distance, while the generator tries to minimize it

$$\min_G \max_{D \in \mathcal{D}} \mathbb{E}_{\mathbf{x} \sim \mathbb{P}_r} [D(\mathbf{x})] - \mathbb{E}_{\tilde{\mathbf{x}} \sim \mathbb{P}_g} [D(\tilde{\mathbf{x}})]$$



K-Lipschitz constraint:

$$|f(x_1) - f(x_2)| \leq K|x_1 - x_2|$$

Wasserstein GANs: keys

- Train the critic more often than the generator to have a good estimation of WD before updating G
- Don't use batch norm on the critic
- Enforce the Lipschitz constraint. Two ways:
 - Gradient clipping (not ideal)
 - Gradient penalty
(<https://arxiv.org/pdf/1704.00028>)

Algorithm 1 WGAN with gradient penalty. We use default values of $\lambda = 10$, $n_{\text{critic}} = 5$, $\alpha = 0.0001$, $\beta_1 = 0$, $\beta_2 = 0.9$.

Require: The gradient penalty coefficient λ , the number of critic iterations per generator iteration n_{critic} , the batch size m , Adam hyperparameters α, β_1, β_2 .

Require: initial critic parameters w_0 , initial generator parameters θ_0 .

```
1: while  $\theta$  has not converged do
2:   for  $t = 1, \dots, n_{\text{critic}}$  do
3:     for  $i = 1, \dots, m$  do
4:       Sample real data  $\mathbf{x} \sim \mathbb{P}_r$ , latent variable  $\mathbf{z} \sim p(\mathbf{z})$ , a random number  $\epsilon \sim U[0, 1]$ .
5:        $\tilde{\mathbf{x}} \leftarrow G_{\theta}(\mathbf{z})$ 
6:        $\hat{\mathbf{x}} \leftarrow \epsilon \mathbf{x} + (1 - \epsilon) \tilde{\mathbf{x}}$ 
7:        $L^{(i)} \leftarrow D_w(\tilde{\mathbf{x}}) - D_w(\mathbf{x}) + \lambda(\|\nabla_{\hat{\mathbf{x}}} D_w(\hat{\mathbf{x}})\|_2 - 1)^2$ 
8:     end for
9:      $w \leftarrow \text{Adam}(\nabla_w \frac{1}{m} \sum_{i=1}^m L^{(i)}, w, \alpha, \beta_1, \beta_2)$ 
10:   end for
11:   Sample a batch of latent variables  $\{\mathbf{z}^{(i)}\}_{i=1}^m \sim p(\mathbf{z})$ .
12:    $\theta \leftarrow \text{Adam}(\nabla_{\theta} \frac{1}{m} \sum_{i=1}^m -D_w(G_{\theta}(\mathbf{z})), \theta, \alpha, \beta_1, \beta_2)$ 
13: end while
```

β -VAE

$$L = \text{RMSE}(\text{input}, \text{output}) + \beta \text{KLD}(p(z|x), \text{gaussian})$$

