

# Reconstruction of GWBs at LISA: SGWBinner and Saqqara

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# Outline

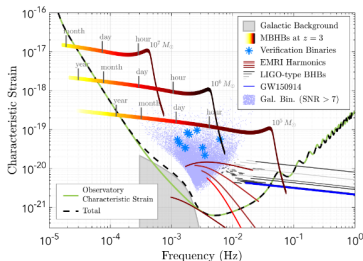
- 1 Introduction
  - Measuring GWBs with LISA
  - Beyond the simplest scenario
  - Data generation and pre-processing
- 2 Traditional techniques and SGWBinner
  - Statistical tools and likelihood
  - SGWBinner
  - Template-based analysis
- 3 SBI for GWB and Saqqara
  - SBI in a nutshell
  - SBI for LISA GWB analysis
- 4 Conclusions and outlook

# Laser Interferometer Space Antenna



Few details on **LISA**:

- First **GW** interferometer **in space**
- Constellation of three satellites
- **2.5 million km** arm lengths
- Peak sensitivity  $10^{-2} \div 10^{-3} \text{ Hz}$
- Three correlated detectors
- Expected launch in mid **2030**
- Operating for **4.5 yrs (nominal)**



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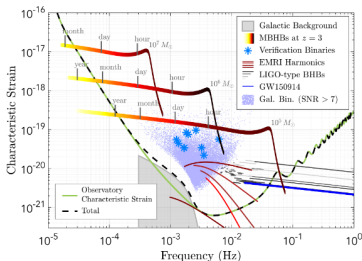


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Very interesting for cosmology  
since we can (among others):

- Measure  $H_0$
- Test modified gravity
- **(Hopefully) detect and characterize GWBs!**



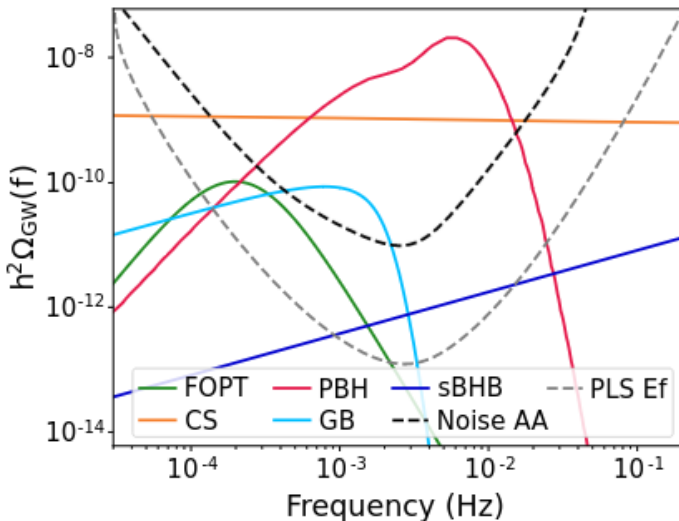
\* Figures from:

<https://www.lisamission.org/multimedia/image/lisa-astro2020>

LISA Collaboration, P. Amaro-Seoane et al., ArXiv: 1702.00786



# Sources of GWBs in the LISA



\* Figure from M. Colpi et al., ArXiv:2402.07571

# Basics of GW data analysis

**Data**  $\tilde{d}$  (in frequency space)  $\longrightarrow \tilde{d} = \tilde{s} + \tilde{n}$

- For individual sources  $\langle \tilde{s} \rangle \neq 0$
- For GWBs  $\langle \tilde{s} \rangle = 0$
- For noise  $\langle \tilde{n} \rangle = 0$

For an **isotropic GWB**  $\longrightarrow \langle h_\lambda(\vec{k}) h_{\lambda'}^*(\vec{k}') \rangle \propto \delta_{\lambda\lambda'} P_h^\lambda(k) \delta(\vec{k} - \vec{k}')$

Assuming  $\langle \tilde{s} \tilde{n} \rangle = 0$  and Gaussian signal and noise

$$\langle \tilde{d}^2 \rangle = \langle \tilde{s}^2 \rangle + \langle \tilde{n}^2 \rangle = \sum_{\lambda} \mathcal{R}_{\lambda} P_h^{\lambda} + N \equiv \mathcal{R} [P_h + S_n]$$

where we have introduced

- The **(quadratic) response function** of the instrument  $\mathcal{R}$
- The (intensity of the) **signal power spectrum**  $P_h$  (in 1/Hz)
- The **noise power spectrum**  $N$  (in 1/Hz)
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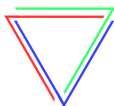
In order to compare with cosmological predictions it's customary to introduce

$$\Omega_{\text{GW}} \equiv \frac{1}{3H_0^2 M_p^2} \frac{\partial \rho_{\text{GW}}}{\partial \ln f} = \frac{4\pi^2}{3H_0^2} f^3 P_h \quad \text{and} \quad \Omega_n(f) = \frac{4\pi^2}{3H_0^2} f^3 S_n(f),$$

where  $H_0 \simeq h_0 \times 3.24 \times 10^{-18} \text{ Hz}$  is the Hubble parameter today.

# Time Delay Interferometry

The simplest option is to  
build three (**correlated**)  
**Michelson-like data streams**

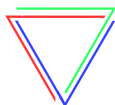


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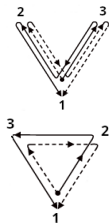
TDI = Combine measurements at different times to achieve noise reduction!  
Using  $\eta_{ij}$  measurement in  $i$  coming from  $j$  and the delay operator  $D_{ij}$  we define:

- **Michelson variables**, dubbed **XYZ**, defined as (YZ are permutations):

$$X \equiv (1 - D_{13}D_{31})(\eta_{12} + D_{12}\eta_{21}) + (D_{12}D_{21} - 1)(\eta_{13} + D_{13}\eta_{31})$$

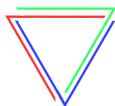
- **Sagnac variables**, dubbed  **$\alpha\beta\gamma$** , defined as ( $\beta\gamma$  permutations):

$$\alpha \equiv \eta_{12} + D_{12}\eta_{23} + D_{12}D_{23}\eta_{31} - (\eta_{13} + D_{13}\eta_{32} + D_{13}D_{32}\eta_{21})$$



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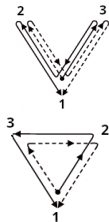
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In these variables, **signal and noise** (in different channels) **are correlated!**

For equal arms, diagonalization via:  
(diagonal variables dubbed AET and  $\mathcal{AET}$ )

$$\rightarrow \begin{pmatrix} -1/\sqrt{2} & 0 & 1/\sqrt{2} \\ 1/\sqrt{6} & -2/\sqrt{6} & 1/\sqrt{6} \\ 1/\sqrt{3} & 1/\sqrt{3} & 1/\sqrt{3} \end{pmatrix} \quad 6/32$$

# The LISA response function

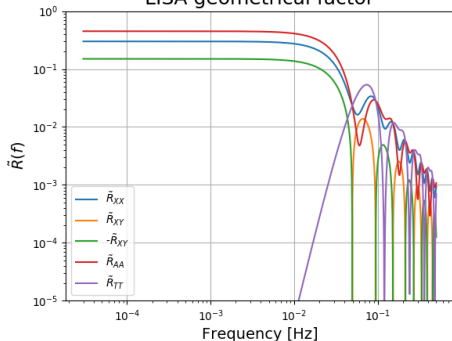
For an **isotropic** and **non-chiral spectrum** we get (see, e.g., 2009.11845):

$$\langle s_i^{TDI} s_j^{TDI} \rangle = \int dk P_h(k) \mathcal{R}_{ij}^{TDI}(k), \quad \mathcal{R}_{ij}^{TDI}(k) \equiv 4 (2\pi kL)^2 |W^{TDI}(kL)|^2 \tilde{R}_{ij}^{TDI}(k).$$

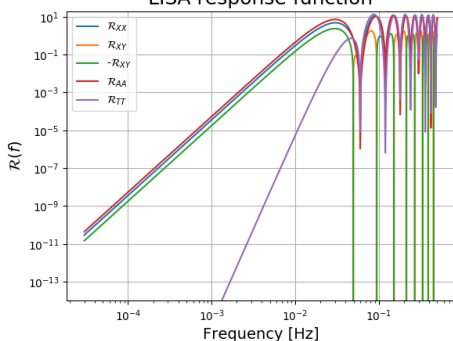
where  $\mathcal{R}_{ij}^{TDI}(k)$  is the **LISA response** and  $\tilde{R}_{ij}^{TDI}(k)$  is a geometrical factor.

For XYZ/AET (AET is  $\sim$  diagonal) combinations we get:

LISA geometrical factor



LISA response function



At low frequencies the TT response is suppressed by a factor  $f^6$ !

See [https://github.com/Maupieronni/GW\\_response](https://github.com/Maupieronni/GW_response)

# The LISA noise model

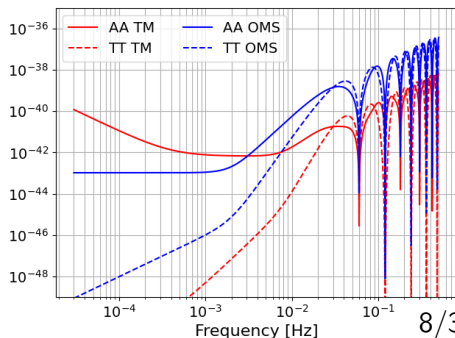
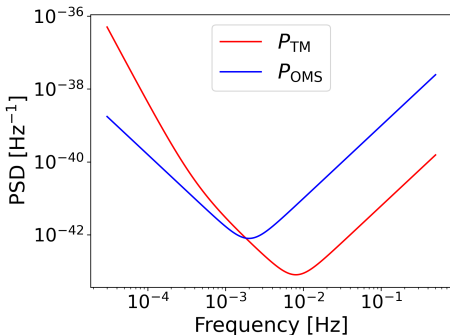
After TDI two main noise components:

Low frequencies are dominated by Test Mass (TM) noise  
large frequencies by Optical Metrology System (OMS) noise:

$$P_{TM}(f, A) = A^2 \times 10^{-30} \times F_{TM}(f),$$

$$P_{OMS}(f, P) = P^2 \times 10^{-24} \times F_{OMS}(f),$$

where  $F_{TM}(f)$ ,  $F_{OMS}(f)$  are some functions of frequency.



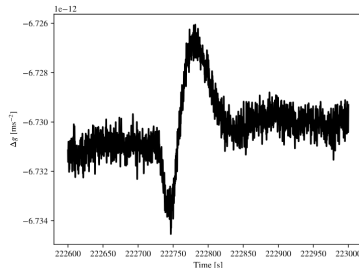
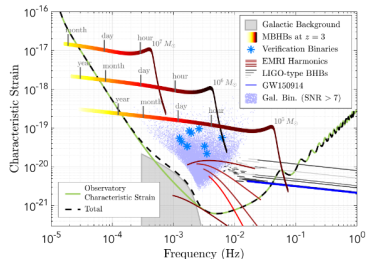
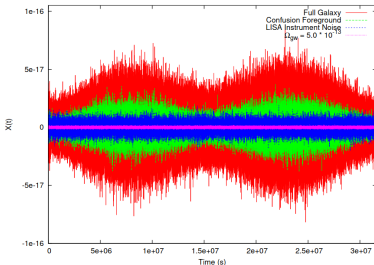


Beyond the simplest scenario

# Stationarity won't hold ...

The LISA data won't be stationary:

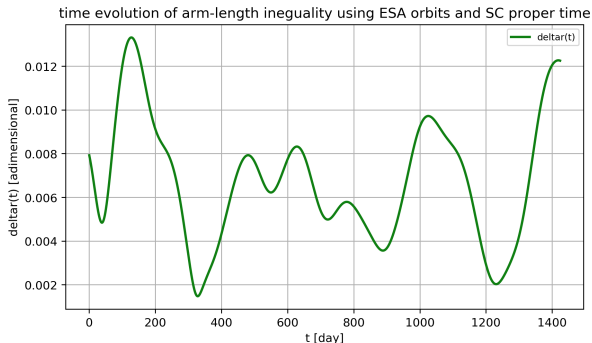
- There will be transient signals
- Measured GWBs change with time
- There will be transient glitches



\* LISA Collaboration, P. Amaro-Seoane et al., ArXiv: 1702.00786. M. R. Adams, Phys. Rev. D 89 (2014), 022001, ArXiv: 1307.4116. Q. Baghi et al., Phys. Rev. D 105 (2022), 042002, ArXiv: 2112.07490.

Beyond the simplest scenario

# ... LISA won't have equal arms...



Fluctuations in the arm-lengths of order up to  $10^{-2}$  are expected!

Response functions and noise spectra will be modified



- Orthogonality of TDI variables might be affected
- T is not signal orthogonal anymore
- ...

An accurate description is necessary to avoid biases in the analysis!

Beyond the simplest scenario

## ... nor the same noise levels in all links!

Let us have a closer look at the problem of noise characterization  
(still stick with TM and OMS noise only with known templates)

Each spacecraft contains two test  
masses and two lasers



12 (6 **Acc** + 6 **OMS**) independent  
noise components are expected!

$$\begin{pmatrix} \textcolor{red}{A} & 0 \\ 0 & \textcolor{blue}{P} \end{pmatrix} \rightarrow \begin{pmatrix} \begin{matrix} \textcolor{red}{A}_{12} & 0 & 0 & \textcolor{red}{D}_{12}\textcolor{red}{A}_{21} & 0 & 0 \\ 0 & \textcolor{red}{A}_{23} & 0 & 0 & \textcolor{red}{D}_{23}\textcolor{red}{A}_{32} & 0 \\ 0 & 0 & \textcolor{red}{A}_{31} & 0 & 0 & \textcolor{red}{D}_{31}\textcolor{red}{A}_{13} \\ \textcolor{red}{D}_{12}\textcolor{red}{A}_{12} & 0 & 0 & \textcolor{red}{A}_{21} & 0 & 0 \\ 0 & \textcolor{red}{D}_{23}\textcolor{red}{A}_{23} & 0 & 0 & \textcolor{red}{A}_{32} & 0 \\ 0 & 0 & \textcolor{red}{D}_{31}\textcolor{red}{A}_{31} & 0 & 0 & \textcolor{red}{A}_{13} \end{matrix} & 0 \\ 0 & \begin{matrix} \textcolor{blue}{P}_{12} & 0 & 0 & 0 & 0 & 0 \\ 0 & \textcolor{blue}{P}_{23} & 0 & 0 & 0 & 0 \\ 0 & 0 & \textcolor{blue}{P}_{31} & 0 & 0 & 0 \\ 0 & 0 & 0 & \textcolor{blue}{P}_{21} & 0 & 0 \\ 0 & 0 & 0 & 0 & \textcolor{blue}{P}_{32} & 0 \\ 0 & 0 & 0 & 0 & 0 & \textcolor{blue}{P}_{13} \end{matrix} \end{pmatrix}$$

Several complications are added in the problem:

- Noise components propagate differently in different TDI variables
- Higher dimensionality of the parameter space
- Correlations between the noise parameters

Again, this requires care!

# Data generation (in frequency domain)

Assuming signal and noise to be Gaussian, stationary, and isotropic independent realizations for each **data segment and frequency** are drawn:

$$\tilde{s}_c(f_i) = \frac{\mathcal{N}(0, \sqrt{\Omega_{\text{GW}}(f_i)}) + i \mathcal{N}(0, \sqrt{\Omega_{\text{GW}}(f_i)})}{\sqrt{2}}$$

$$\tilde{n}_c(f_i) = \frac{\mathcal{N}(0, \sqrt{\Omega_n(f_i)}) + i \mathcal{N}(0, \sqrt{\Omega_n(f_i)})}{\sqrt{2}}$$

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Given that:

- LISA will be operating for **4yrs** (and assume also **75% efficiency**)
- We choose **data segments** of **roughly 12 days**

in practice we have:

- Roughly **95** independent **measurements at each frequency**.
- A frequency **resolution** of **around  $10^{-6}$  Hz**

This implies:  $\sim 5 \times 10^5 \times 95$  points in total (per channel), which is a lot!

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- We **average over the (95) data segments**:

This leaves us with some  $D(f_i)$  (the averaged data) and an estimate of the error  $\sigma(f_i)$  (the standard deviation or the data).



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*i.e.* from the initial linear  $10^{-6}$  Hz spacing ( $\sim 5 \times 10^5$  points)  
→ we go to some final (and less dense) set of frequencies  $f_i$   
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To gain a factor  $\sim \mathcal{O}(100 \times 100)$  in computation time!

# Data modeling and likelihood

To perform the analysis (in a Bayesian framework) we need to specify

$$p(\theta|\tilde{d}) = \mathcal{L}(\tilde{d}|\theta)\pi(\theta)/\pi(\tilde{d}) ,$$

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Whittle likelihood should work (see any of the existing reviews):

$$-2 \ln \mathcal{L}(\tilde{d}|\theta) \propto \sum_f \tilde{d}_i C_{ij}^{-1}(f|\theta) \tilde{d}_j^* + \ln [\det C_{ij}(f|\theta)] ,$$

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For fast estimates of the uncertainties on parameter reconstruction we can use the Fisher Information Matrix (FIM):

$$F_{ij} \equiv - \left. \frac{\partial^2 \ln \mathcal{L}(\tilde{d}|\theta)}{\partial \theta_i \partial \theta_j} \right|_{\theta_0} = \sum_f \text{Tr} \left[ C^{-1} \frac{\partial C}{\partial \theta_i} C^{-1} \frac{\partial C}{\partial \theta_j} \right] ,$$

NB



- FIM only works if the posterior is Gaussian
- FIM won't tell us anything about possible biases

# An accurate likelihood for the compressed data

What about the compressed data??

A Gaussian likelihood would give a systematic low bias!

(astro-ph/9808264, astro-ph/0205387, astro-ph/0302218, 0801.0554)

Consider the Gaussian likelihood:

$$\ln \mathcal{L}_G(\vec{\theta}, \vec{n}) \propto -\frac{N_{\text{chunks}}}{2} \sum_{i,j} \sum_k w_{ij}^{(k)} \left( \frac{D_{ij}^{(k)} - h^2 \Omega_{\text{GW}}(f_{ij}^{(k)}, \vec{\theta}) - h^2 \Omega_{n,ij}(f_{ij}^{(k)}, \vec{n})}{h^2 \Omega_{\text{GW}}(f_{ij}^{(k)}, \vec{\theta}) + h^2 \Omega_{n,ij}(f_{ij}^{(k)}, \vec{n})} \right)^2$$

and the Lognormal likelihood:

$$\ln \mathcal{L}_{LN}(\vec{\theta}, \vec{n}) \propto -\frac{N_{\text{chunks}}}{2} \sum_{i,j} \sum_k w_{ij}^{(k)} \ln^2 \left( \frac{h^2 \Omega_{\text{GW}}(f_{ij}^{(k)}, \vec{\theta}) + h^2 \Omega_{n,ij}(f_{ij}^{(k)}, \vec{n})}{D_{ij}^{(k)}} \right)$$

Then we define our likelihood as (astro-ph/0302218, 2009.11845)

$$\ln \mathcal{L} = \frac{1}{3} \ln \mathcal{L}_G + \frac{2}{3} \ln \mathcal{L}_{LN}$$

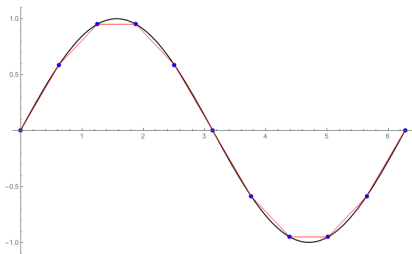
which includes the skewness contributions and thus is more accurate.

# SGWBinner algorithm

We look for **best approximation** of the signal **with a multi-PL**

$$h^2\Omega_{\text{GW}}(f, \vec{\theta}) = \sum_i 10^{\alpha_i} \left( \frac{f}{\sqrt{f_{\min,i} f_{\max,i}}} \right)^{p_i} \Theta(f - f_{\min,i}) \Theta(f_{\max,i} - f) .$$

where  $\Theta$  is the Heaviside step function.



A sketch of the algorithm:

- 1 Build a robust noise prior
- 2 Bin the frequency range and reconstruct the signal
- 3 Merge as many bins as possible (to avoid overfitting)
- 4 Define a procedure to compute the error on the reconstruction
- 5 Final MCMC run with common noise parameters

# Criterion for merging

Two motivations for merging:

- Larger  $N$  means smaller bins which implies larger errors
- For large values of  $N$ , the reconstruction with  $N$  bins (i.e.  $2N$  parameters) may overfit the signal

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For a couple of consecutive bins  $(i, i + 1)$  we can compute

$$\begin{aligned}\Delta \text{AIC} &= \text{AIC}_{\text{after merging}} - \text{AIC}_{\text{before merging}} \\ &= \chi_{\text{after merging}}^2 - \chi_{\text{before merging}}^2 - 2 k_{1\text{-bin}}\end{aligned}$$

where the Akaike Information Criterion (AIC) is  $\text{AIC} \equiv \chi^2 + 2k$ .

In practice:

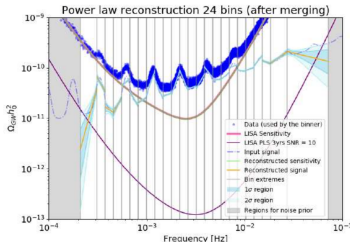
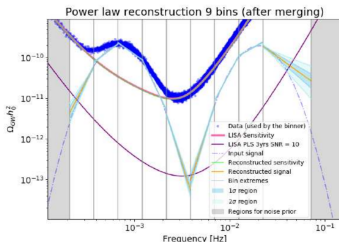
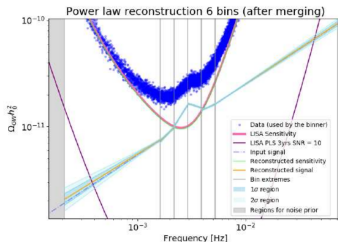
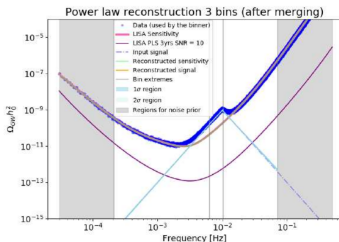
$$\Delta \text{AIC} < 0$$

→

**It is convenient to merge the two bins**

# Frequency shape reconstruction

Some examples of reconstructions with the SGWBinner code

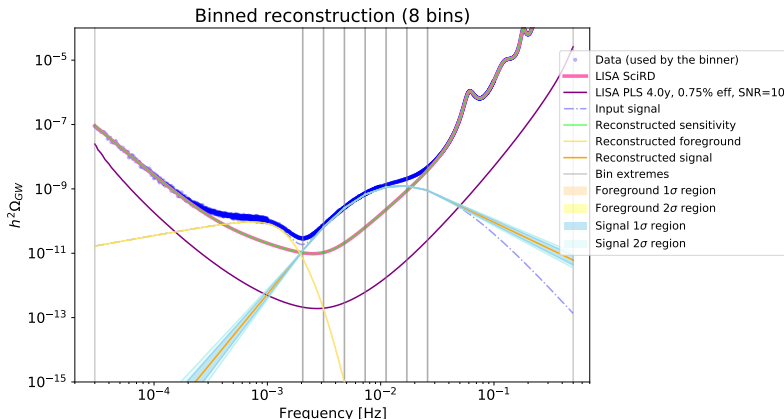


# Joint treatment of SGWB + noise + foreground

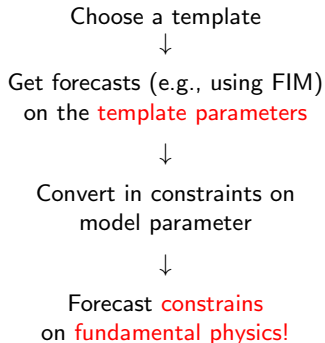
The code can work with several components in the data!

Consider for example the signal due to Galactic binaries:

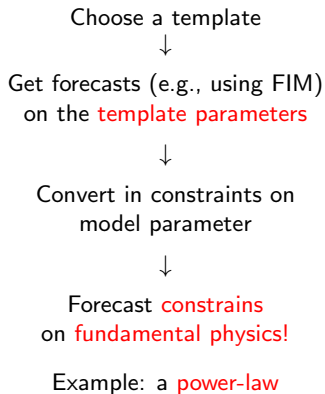
$$h^2\Omega_{\text{GW}} = 10^{\alpha_{\text{FG}}} f^{2/3} e^{-a_1 f + a_2 f \sin(a_3 f)} \{1 + \tanh[a_4(f_k - f)]\} .$$



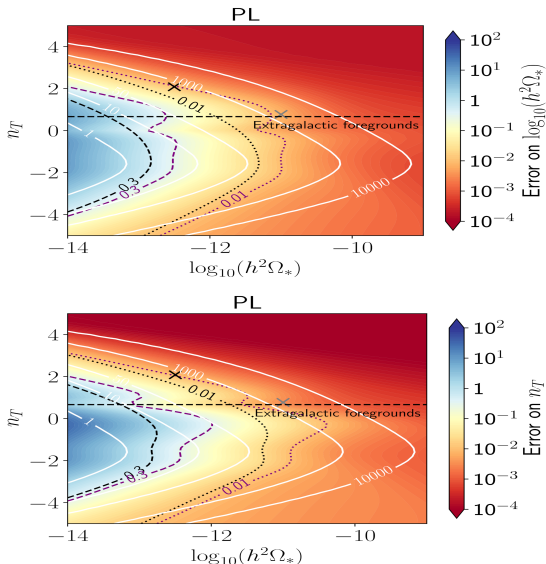
# Forecasting LISA constraints I (FIM)



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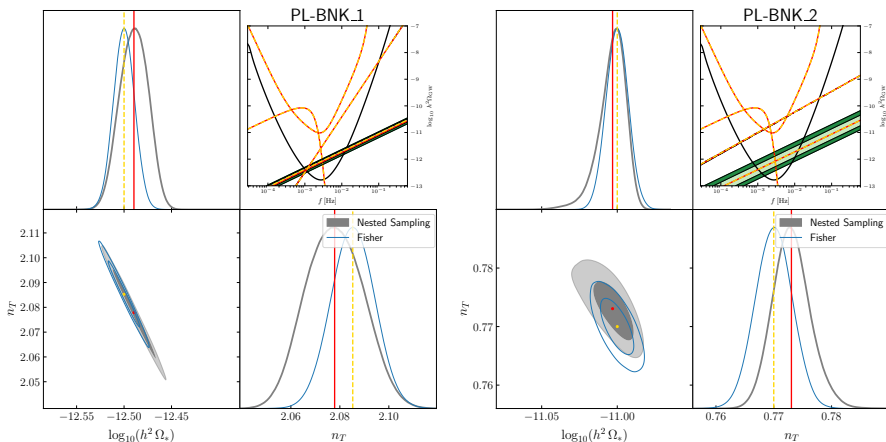


$$\Omega_{\text{GW}} h^2 = 10^{\log_{10}(h^2 \Omega_*)} \left( \frac{f}{f_*} \right)^{n_T}$$



# Forecasting LISA constraints II (Full analysis)

Validate FIM results generating data and running some data analysis pipeline

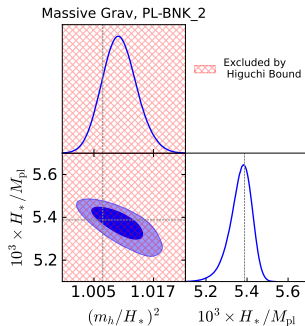
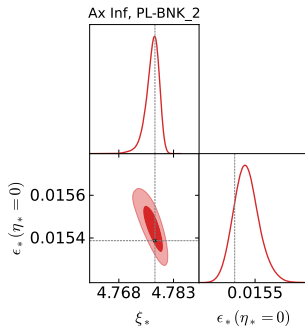


LISA Cosmology Working Group, JCAP 11 (2024) 032, ArXiv:2405.03740.

# Forecasting LISA constraints III (model parameters)

Again PL  
(from inflation)

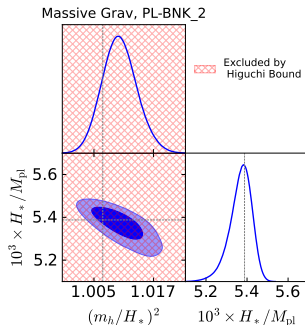
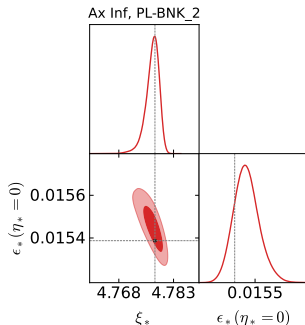
LISA Cosmology  
Working Group,  
JCAP 11 (2024) 032,  
ArXiv:2405.03740.



# Forecasting LISA constraints III (model parameters)

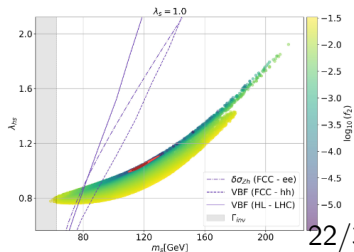
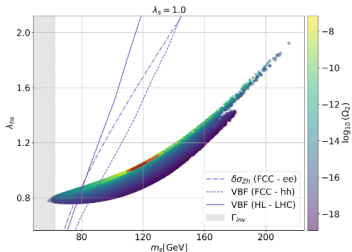
Again PL  
(from inflation)

LISA Cosmology  
Working Group,  
JCAP 11 (2024) 032,  
ArXiv:2405.03740.



Or a BPL  
(from FOPTs)

LISA Cosmology  
Working Group,  
JCAP 10 (2024) 020,  
ArXiv:2403.03723.





## Also more complex noise ...

Let's consider a more  
complex noise model

- 6 TM parameters
- 6 OMS parameters

Does that impact  
the signal reconstruction?

## Template-based analysis

## Also more complex noise ...

Let's consider a more complex noise model

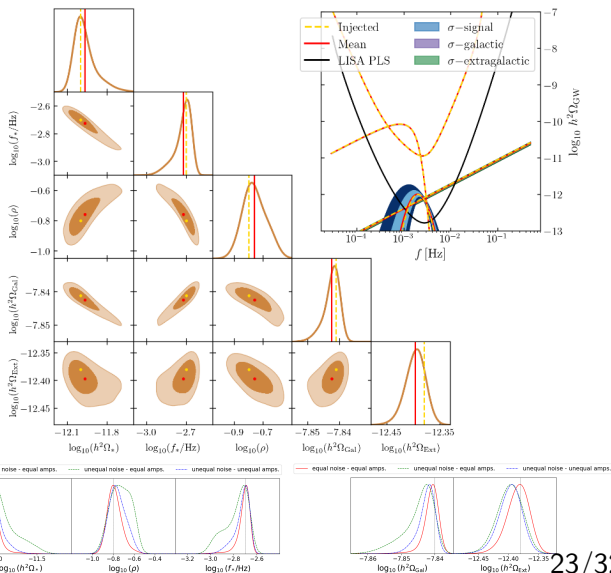
- 6 TM parameters
- 6 OMS parameters

Does that impact the signal reconstruction?

Tested for:

- Power Law  
Hartwig et al.  
Phys.Rev.D 107 (2023), 123531,  
ArXiv: 2303.15929.
- Lognormal bump  
Kume et al. ArXiv: 2410.10342.

Seems like not much!





# SBI for GWB data analysis

Traditional methods (MCMC, nested sampling, whatever) are quite efficient and guaranteed to converge (in some cases)

**but**

scale poorly with number of parameters and require explicit likelihoods

Can alternative approaches perform better in some cases?

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Normally, with Bayesian inference, we try to study the posterior probability:

$$p(\theta|d) = \frac{p(d|\theta) \pi(\theta)}{p(d)} \equiv r(d, \theta) \pi(\theta) ,$$

where we have introduced:

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i.e.,  $r(d, \theta)$  is the ratio between joint probability and marginal probability.

Given a pair  $(\theta, d)$ ,  $r(d, \theta)$  can be used to assess whether  $\theta$  can generate  $d$ !

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Given a pair  $(\theta, d)$ ,  $r(d, \theta)$  can be used to assess whether  $\theta$  can generate  $d$ !

This can be cast in a minimization problem that can be solved with ML the approach is typically referred to as **Neural Ratio Estimation (NRE)** (basically build a classifier to say whether  $\theta, d$  are joint or marginal...).

# A very simple example

Let's consider:

$$d = \theta^2 + \epsilon$$

with

$$\theta \sim U[-1, 1]$$

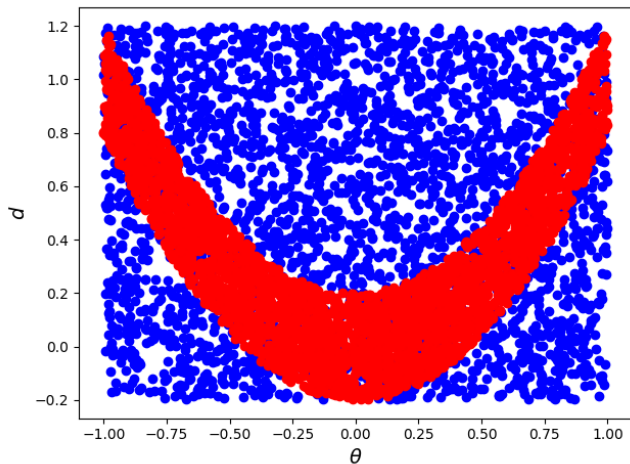
$$\epsilon \sim U[-.2, .2]$$

Marginal samples

$$d, \theta \sim p(d)p(\theta)$$

Joint samples

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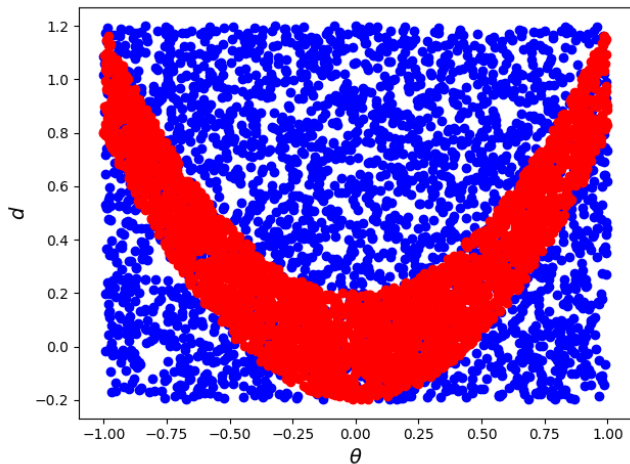
$$\epsilon \sim U[-.2, .2]$$

Marginal samples

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Joint samples

$$d, \theta \sim p(d, \theta)$$



In very large parameter spaces you can target a subset of the parameters!

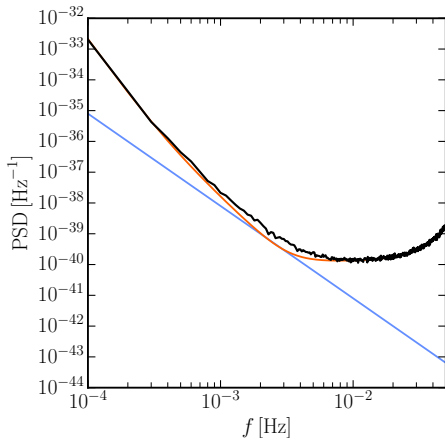


Automatically marginalize over the other parameters (here  $\epsilon$ )!



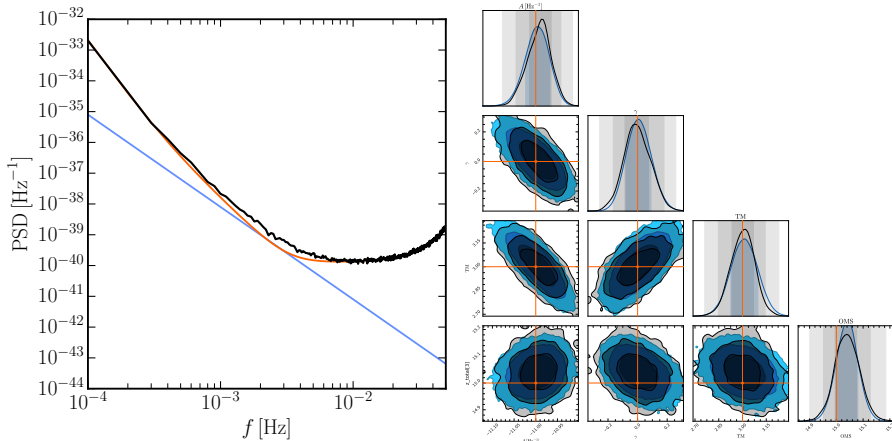
# Recover previous results ...

Assume we inject a power law signal:  
Can we recover it with the same level of accuracy?



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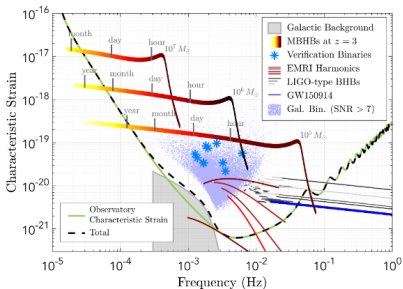
Good news!

James Alvey et al., Phys. Rev. D 109 (2024) 083008, ArXiv:2309.07954.

Code available at <https://github.com/PEREGRINE-GW/saqqara/>

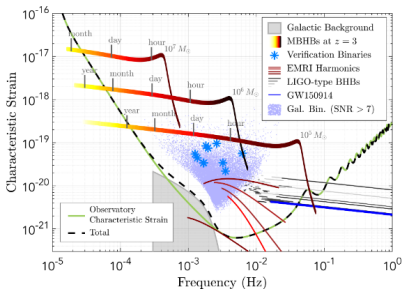
# ... plus something completely new!

What if there's something else  
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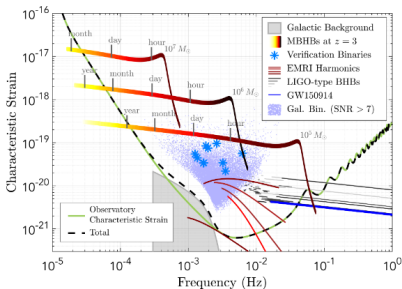
A **minimal setup** for this:  
randomly inject transients slightly  
below the threshold for detection

Would this still work??

## SBI for LISA GWB analysis

## ... plus something completely new!

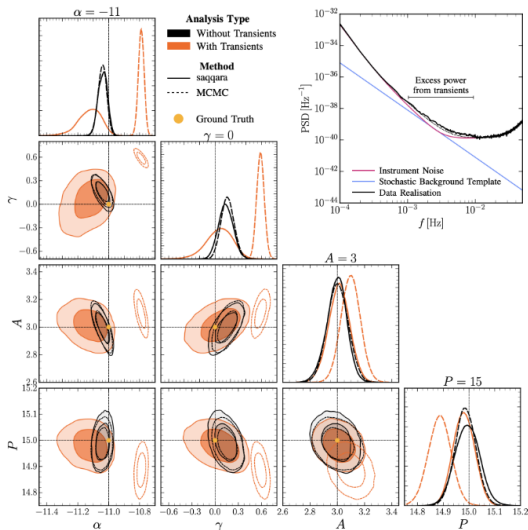
What if there's something else  
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A **minimal setup** for this:  
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Would this still work??

**Yes!!**



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The **noise won't be stationary** for the  
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How does this impact the signal  
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**A strategy** to answer this question:

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- 2 Analyze segment-by-segment  
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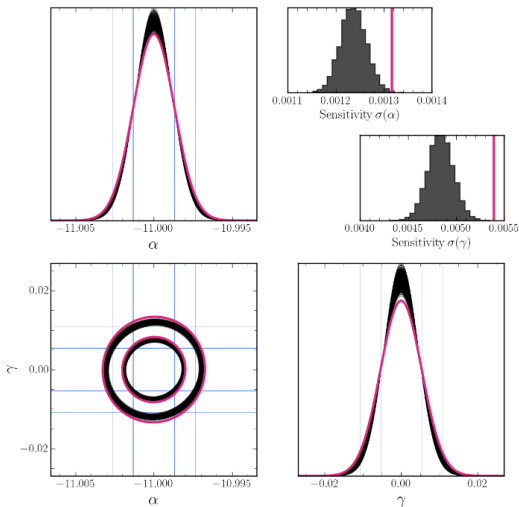
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**A strategy** to answer this question:

- 1 Cut the data into segments (where stationarity holds)
- 2 Analyze segment-by-segment (FIM or training a network)
- 3 Combine the results (assuming each segment is an independent draw)

First test with FIM:

**Looks like you actually do better!**



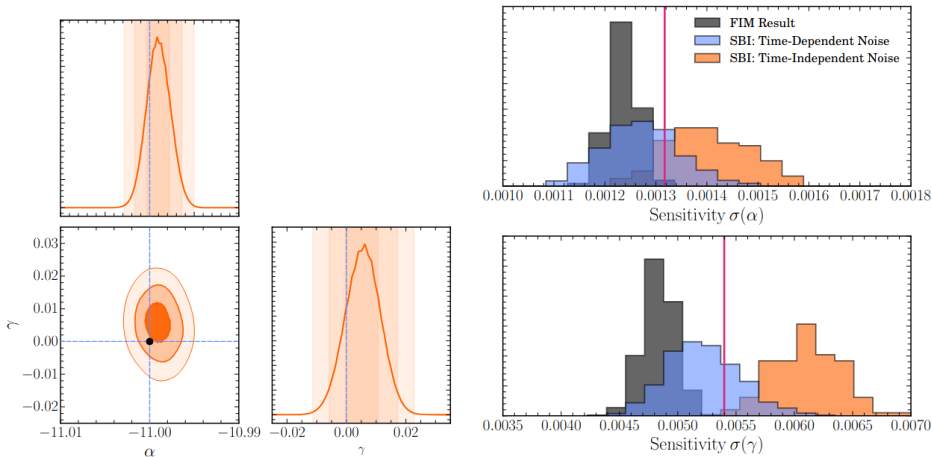
James Alvey et al., ArXiv:2408.00832.

Code available at <https://github.com/PEREGRINE-GW/saqqara/>  
See also [https://github.com/MauroPieroni/GW\\_response](https://github.com/MauroPieroni/GW_response)



# What about noise non-stationarities? (Full analysis)

Validate FIM results with a full analysis



Moreover, training segment-by-segment is 100 times faster!

James Alvey et al., ArXiv:2408.00832.

Code available at <https://github.com/PEREGRINE-GW/saqqara/>

See also [https://github.com/Mauropieroni/GW\\_response](https://github.com/Mauropieroni/GW_response)

# Conclusions and outlook

## Conclusions

- Analyzing LISA data will be quite difficult
- Agnostic (or at least not very signal dependent) methods are useful
- Traditional methods work (but they might be expensive)
- SBI (and ML in general) looks quite promising ...
- ... it works with transients and non-stationarities in the noise!

## Future perspectives

- Keep improving on detector modeling
- More realistic noise model and data generation procedure
- Include anisotropies in the signal
- New ideas/techniques?
- ...

Last slide

Thank you for your attention!